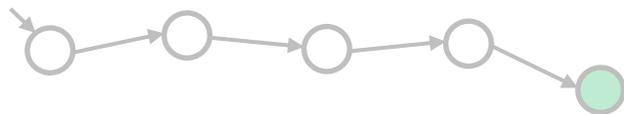
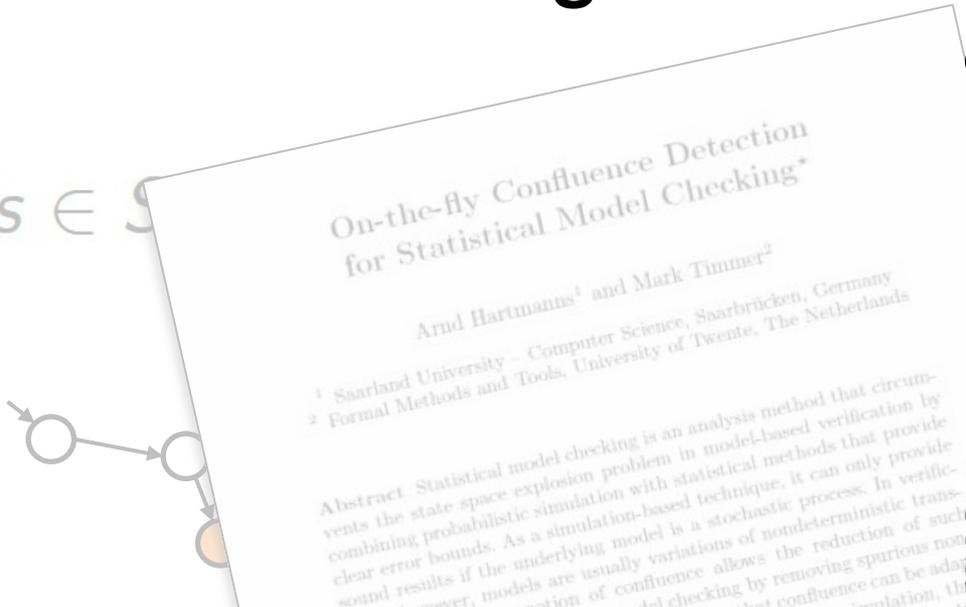
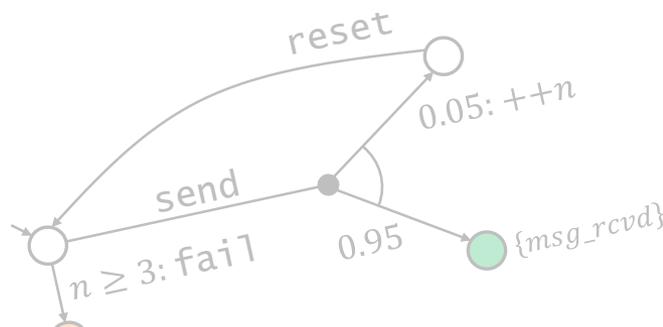


On-the-fly Confluence Detection for Statistical Model Checking

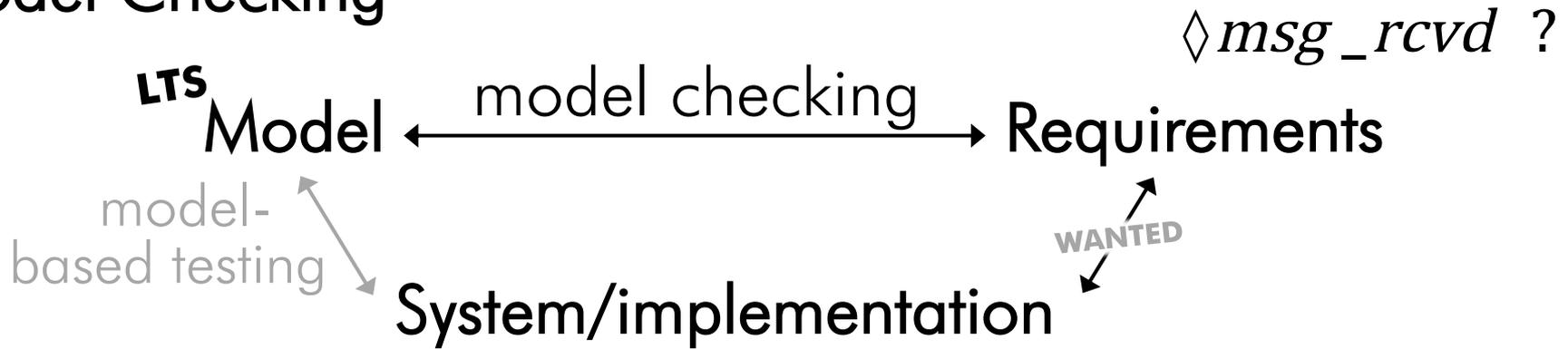
+ very low m
no change



$$\mu(S_i) = \nu(s_i) \wedge (S_i = \{s_i\} \vee \forall s \in S$$



Model Checking

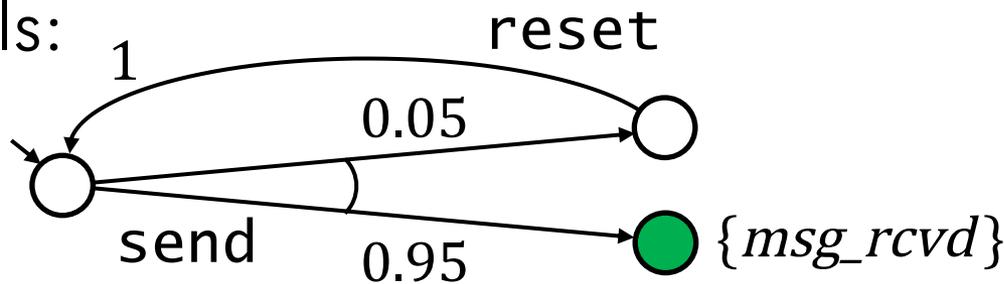


Problem: State-space explosion **memory consumption**

Probabilistic Model Checking

$P(\diamond msg_rcvd) \geq 0.99 ?$

DTMC models:

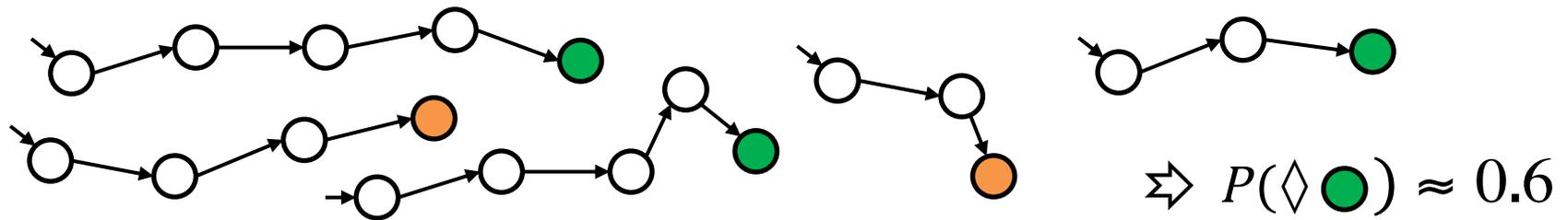


runtime stability

Problem: State-space explosion plus numerical complexity

Statistical Model Checking ^{SMC}

$SMC = \text{Simulation} + \text{Statistics}$



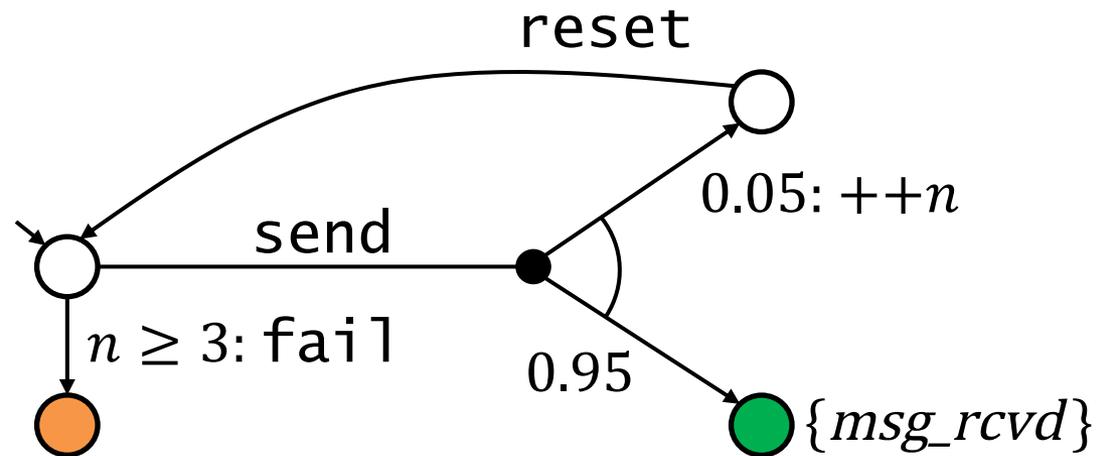
...confidence intervals, Chernoff-Hoeffding bound, SPRT...
error bounds: e.g. result is ε -correct with probability δ

- +** constant memory usage (store only current state)
no numeric surprises (e.g. with imprecise arithmetics)
- runtime strongly dependent on desired accuracy

Statistical Model Checking versus Nondeterminism

MDP^{/PA} models:


simulation



⇒ need to resolve
nondeterministic choices

$$P_{\min}(\diamond msg_rcvd) \geq 0.99 \quad ?$$
$$P_{\max}(\diamond msg_rcvd) \geq 1 \quad ?$$

Standard technique:

 **implicit** uniformly distributed resolution

⇒ some value $\in [P_{\min}, P_{\max}]$

widely implemented:
PRISM, UPPAAL, ...

Introduction

Previous approaches to SMC for MDPs

"POR"

Partial order reduction-based method:



Nondeterminism may be **spurious**

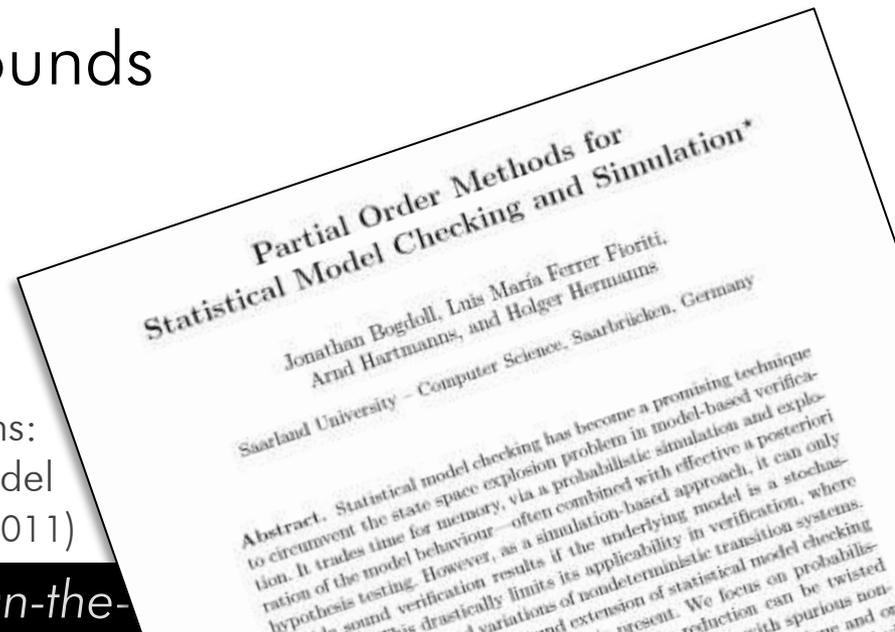
= irrelevant for the results, i.e. $P_{\min} = P_{\max}$

⇒ check for spuriousness on-the-fly and ignore

+ very low memory overhead
no change to SMC error bounds

- spurious interleavings only

Bogdoll, Ferrer Fioriti, H., Hermanns:
Partial Order Methods for Statistical Model
Checking and Simulation (FMOODS/FORTE 2011)



Introduction

Previous approaches to SMC for MDPs

Learning-based method:



Use reinforcement learning to obtain memoryless scheduler using simulation

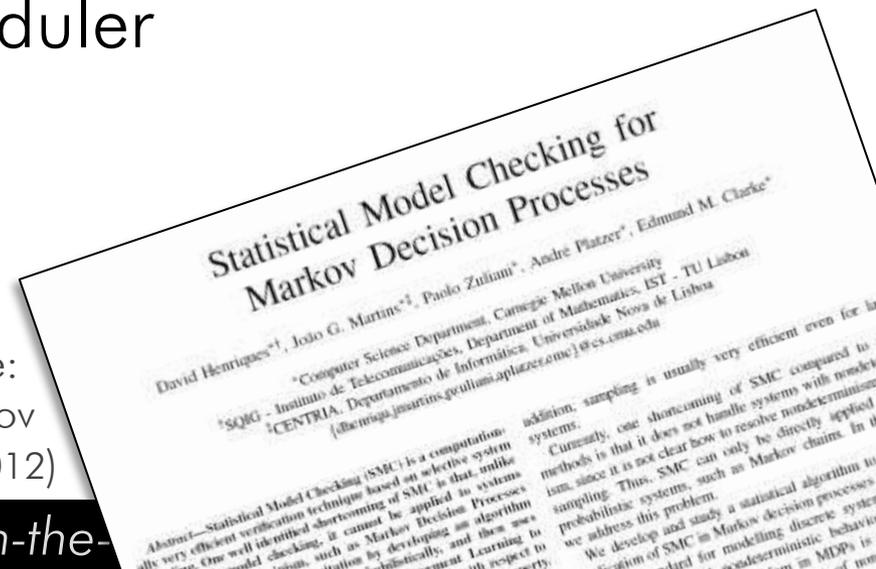
**technique
from AI**

⇒ use that scheduler for SMC for P_{\max} (bounded LTL)

+ works for every MDP

- memory usage to store scheduler
no error bounds, converges
to actual result only

Henriques, Martins, Zuliani, Platzer, Clarke:
Statistical Model Checking for Markov
Decision Processes (QEST 2012)



In this talk: a new method
based on **on-the-fly confluence detection** 

1 Probabilistic Confluence

Adaption to SMC & advantages over POR

(MT)

2 On-the-fly Detection

A correct algorithm for use during simulation

(MT)

3 Evaluation

Tools, applicability, performance

Hartmanns, Timmer: On-the-fly
Confluence Detection for Statistical
Model Checking (NFM 2013)

On-the-fly Confluence Detection
for Statistical Model Checking*

Arnd Hartmanns¹ and Mark Timmer²

¹ Saarland University – Computer Science, Saarbrücken, Germany
² Formal Methods and Tools, University of Twente, The Netherlands

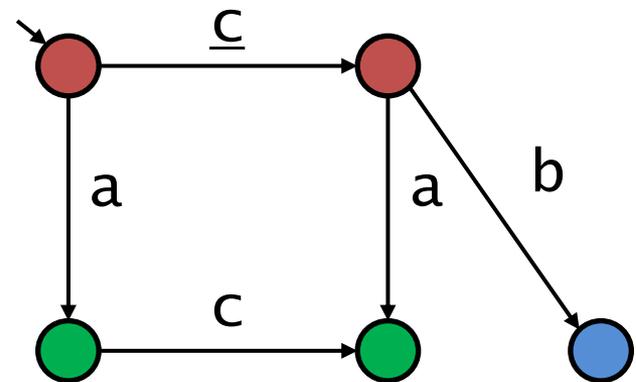
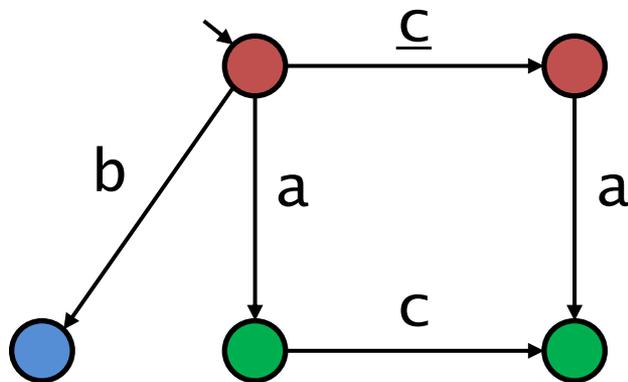
Confluence

Transitions can sometimes be given priority:

- Stuttering
- Nonprobabilistic

**Just like
for POR**

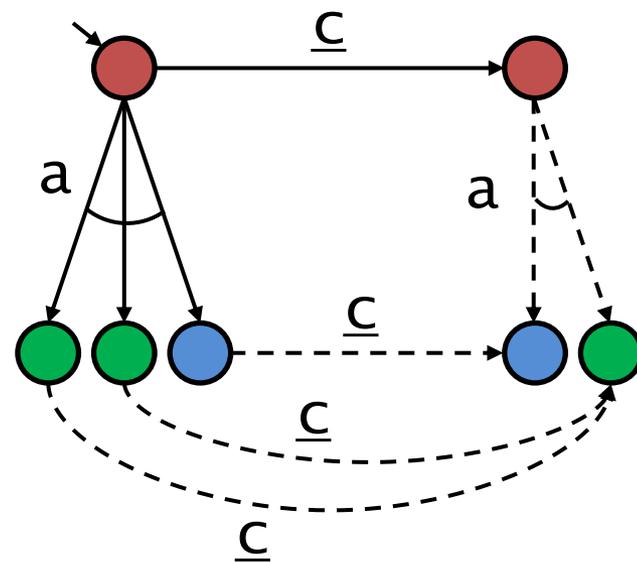
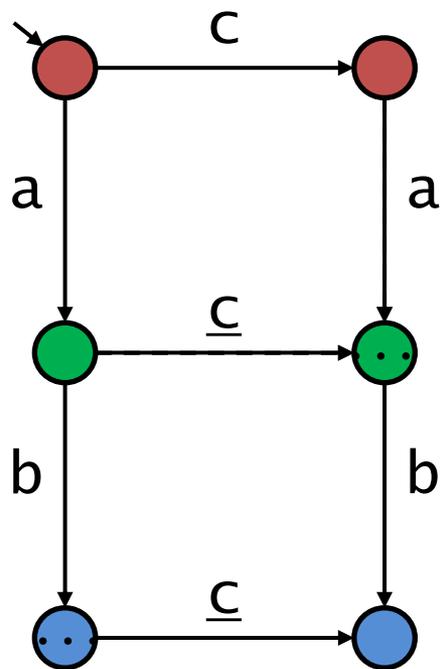
Invisible transitions may *disable* behaviour...
though often they *connect equivalent states*



Confluence

How to be sure?

⇒ Check *confluence diagram* for a set of transitions

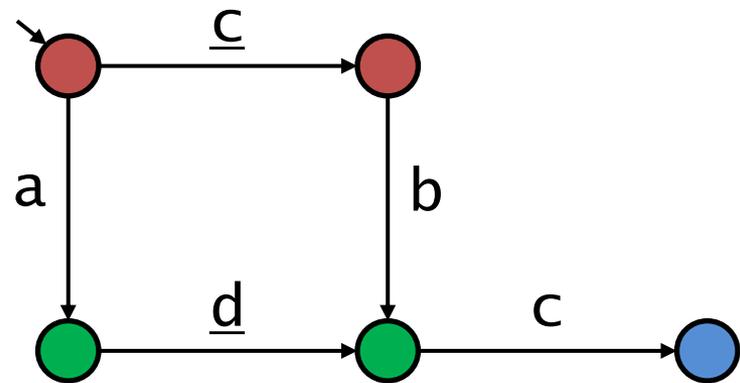
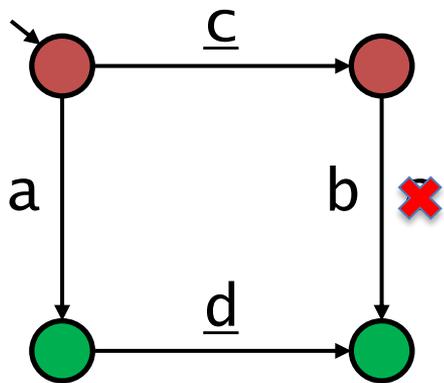


**Probabilities
should match**

Confluence for SMC

We relax a previous notion in three ways:

1. Transitions may be mimicked by *different actions*
2. Transitions have to be stuttering and nonprobabilistic *only locally*
3. Distributions may be related in a *more liberal* way



Confluent transitions can still be given priority while preserving all properties in PCTL^{*}_{-X}

Confluence versus POR

Partial Order Reduction:

- Preserves *probabilistic* LTL_{-X}
- Based on *independent actions* and *ample sets*
- Allows ample actions to be *probabilistic*

Advantage: can prioritise probabilistic transitions
Disadvantage: not defined for concrete state spaces

**reduction powers
incomparable**

Confluence Reduction:

- Preserves $PCTL^*_{-X}$
- Based on *confluent transitions* (*commuting diagrams*)

Advantage: defined for concrete state spaces
Disadvantage: cannot prioritise probabilistic transitions

On-the-fly detection

Simulation / SMC using on-the-fly confluence detection:

Upon arrival at a nondeterministic state:

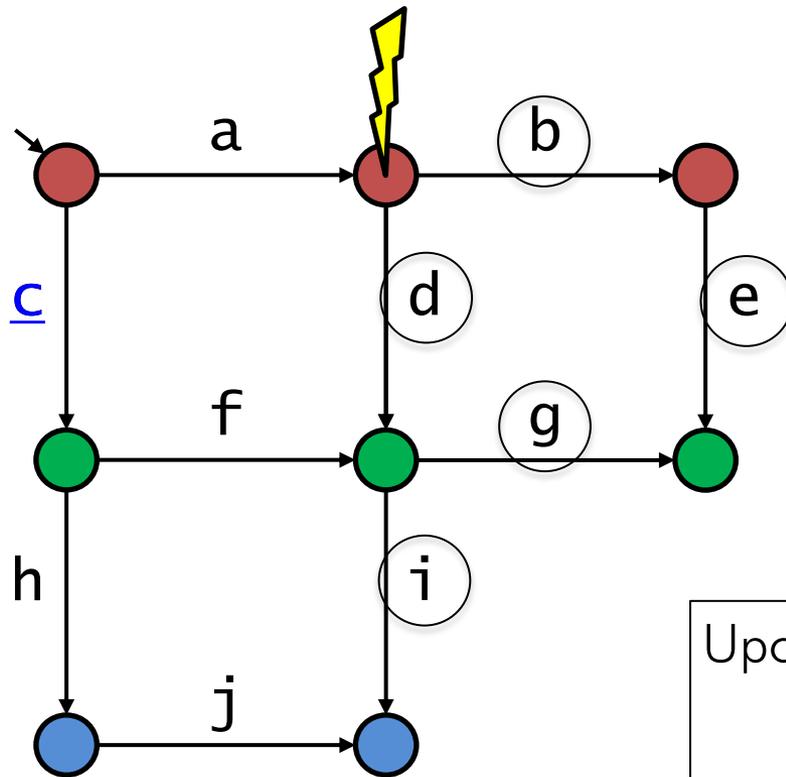
- 
- Look for at least one outgoing confluent transition
 - If no such transition is found, **abort** (or try **POR**)
 - If at least one transition is found, **take it**

1. Check if it is *nonprobabilistic* and *stuttering*
2. Check if all its neighbouring transitions are mimicked
(**recursion**)

Careful: ignoring problem

⇒ Check if at least every l steps a state is *fully explored*

On the fly detection



-  Check if it is nonprobabilistic and stuttering
-  Check if all its neighbouring transitions are mimicked

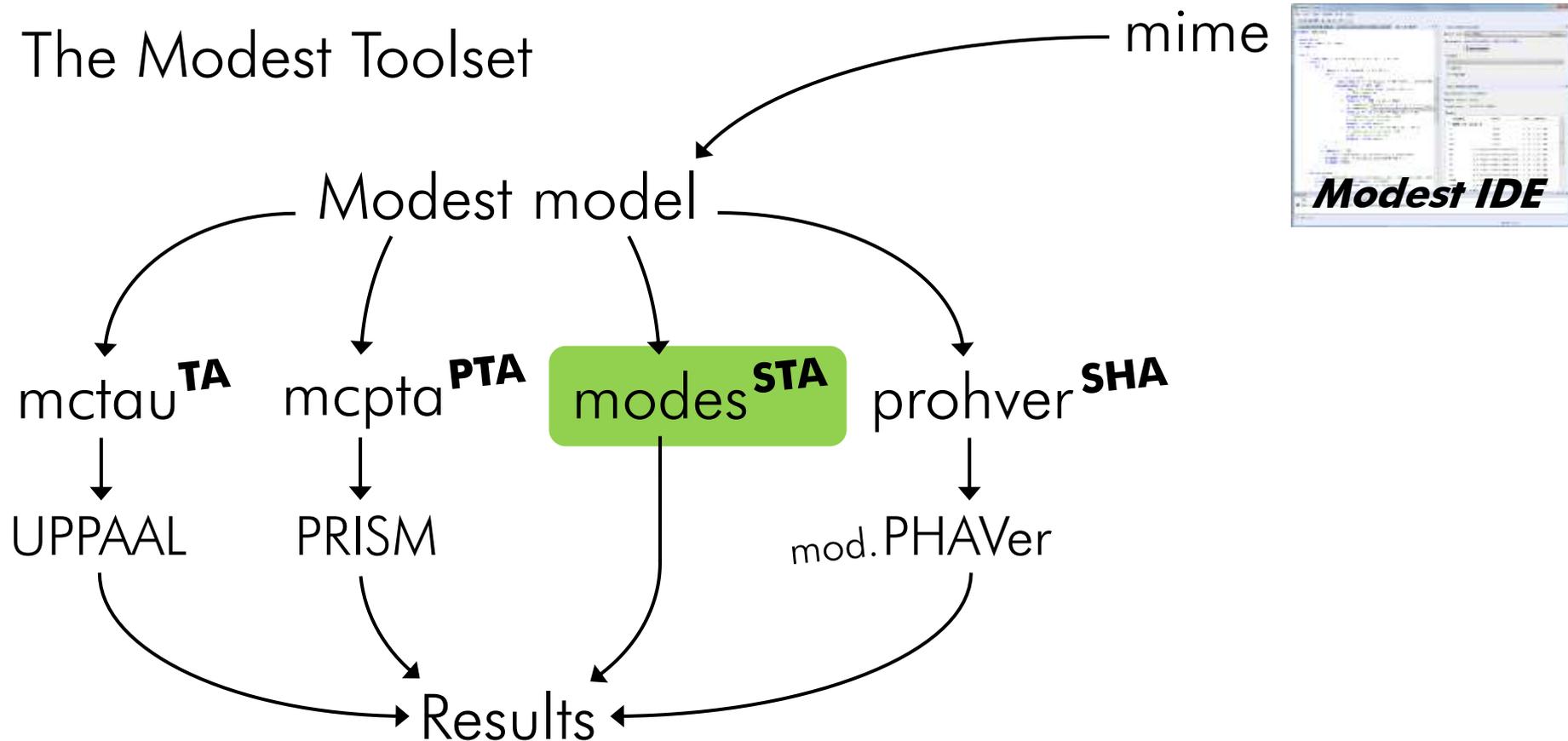
Upon arrival at a nondeterministic state:

- Look for at least one outgoing confluent transition

➡ If no such transition is found, **abort**

➡ If at least one transition is found, **take it**

The Modest Toolset



modes: SMC for Modest/STA
⇒ MDP as special case
POR + Confluence

NEW



www.modestchecker.net

Examples

Dining Cryptographers **PRISM model**

N cryptographers, two neighbours each

Nondeterminism: communication order

POR confluence



CSMA/CD **"DPTA"**

Two senders, one shared channel, collisions

Nondeterministic choice of station inside channel



BEB (Bounded Exponential Backoff)

Detailed MDP model of exponential backoff

K: max. backoff, N: n° of retries, H: n° of hosts

huge state space



Evaluation

Results ^{reachability properties}

(10000 runs $\rightarrow \epsilon < 0.01, \delta > 0.98$)

model	params	uniform:	partial order:			confluence:					model checking:	
		time	time	k	s	time	k	s	c	t	states	time
dining crypto- graphers (N)	(3)	1 s	–	–	–	3 s	4	9	4.0	8.0	609	1 s
	(4)	1 s	–	–	–	11 s	6	25	6.0	10.0	3 841	2 s
	(5)	1 s	–	–	–	44 s	8	67	8.0	12.0	23 809	7 s
	(6)	1 s	–	–	–	229 s	10	177	10.0	14.0	144 705	26 s
	(7)	1 s	–	–	–	–	–	–	–	–	864 257	80 s
CSMA/CD (RF, BC_{max})	(2, 1)	2 s	–	–	–	4 s	3	46	5.4	16.4	15 283	11 s
	(1, 1)	2 s	–	–	–	4 s	3	46	5.4	16.4	30 256	49 s
	(2, 2)	2 s	–	–	–	10 s	3	150	5.1	16.0	98 533	52 s
	(1, 2)	2 s	–	–	–	10 s	3	150	5.1	16.0	194 818	208 s
BEB (K, N, H)	(4, 3, 3)	1 s	3 s	3	4	1 s	3	7	3.3	11.6	$> 10^3$	> 0 s
	(8, 7, 4)	2 s	7 s	4	8	4 s	4	15	5.6	16.7	$> 10^7$	> 7 s
	(16, 15, 5)	3 s	18 s	5	16	11 s	5	31	8.3	21.5	– memout –	–
	(16, 15, 6)	3 s	40 s	6	32	34 s	6	63	11.2	26.2	– memout –	–

+ performance on BEB
& CSMA/CD models
+ vs. model-checking

+ a bit faster than POR
– does not work well for
dining cryptographers

Conclusion

A new approach to SMC for MDPs
based on **on-the-fly confluence detection** 

- detect confluence on-the-fly on the concrete state space
- handle more kinds of nondeterminism than POR method

approach	nondeterminism	probabilities	memory	error bounds
POR	spurious interleavings	$P_{\max} = P_{\min}$	$s \ll n$	unchanged
⇒ confluence	confluent spurious	$P_{\max} = P_{\min}$	$s \ll n$	unchanged
learning	any	P_{\max} only	$s \rightarrow n$	convergence

See also

www.modestchecker.net

& H, T.: On-the-fly Confluence
Detection for Statistical
Model Checking (NFM 2013)

